The University of Jordan School of Engineering											
D	epartm	ent	Course	Course Name			Course Number		Semester		
Mechar	nical En	gineering	Contr	Control Lab			0904419				
2019 Course Catalog Description											
The lab consists of experiments that are related to: First and second order system analysis control experiments. Servo systems. Stability of dynamical systems. System identification. Design and tuning of a PID controller in closed loop systems. Simulation of systems using Simulink or Matlab.											
				Inst	ructors						
	Nam	e	E-mail	E-mail Sec Office H			lours		Lecture Time		
				Text	Books						
			Text	book			Text book 2				
Title			Control Lab Manual				(Handouts				
Author(Dr. Musa Abdalla				-				
Publishe	er, Year	, Edition	Current								
					erences						
	Books 1. K. Ogata, Modern Control Engineering Prentice Hall 2. R Dorf and Bishop, Modern Control System, Prentice Hall 3. B. Kuo, Automatic Control System, Wiley										
Internet	links	The UoJ I	ELearning: <u>elearning.ju.ec</u>	lu.jo							
]	Prere	quisites						
Prerequ	isites by	[,] topic	System Dynamics and Control Fundamentals: Response, Stability, Identification and PID								
Prerequ			0904418 System Dynamics and Control								
-	Co-requisites by course		-								
Prerequ	isite for										
				opics	Covered						
Week 1	Oriente	tion and as	Topics ing over the lab rules and safety				Chapter	in Text	Sections		
		U	<u> </u>				Intro				
2	Simulating first order dynamical systems using Analog Comput						Exp I Lecture Notes				
3	Understanding Servo Systems using Simulink				C C			es			
4	Servos: DC Motor Position Control (2 nd order system performance)						Exp II				
5	Servos: DC Motor Speed Control (1 st order system performance						Exp III				
6	Process Control						Exp IV				
7	Understanding Stability using Simulink						Lecture Notes				
8	Twin Rotor Chopper						Exp V				
9	Understanding PID controllers and Tuning using Matlab						Lecture Notes				
10	PID Controller Design and Tuning						Exp VI				
11	Understanding frequency based system identification using Matlah					Ι	Lecture Notes				
12	System Identification in Frequency Domain					F	Exp VII				
13-15	Final Lab Project										

Mapping of Course Outcomes to ABET Student Outcomes											
SO	s	s Course Outcomes									
1		 Model and Formulate the dynamic systems mathematically Design a PID based controllers to meet the design desired specifications 									
2		e			U I		C1 · 1·				
		0	d a dynamic sys								
5			d present results			-					
6	0.10	5. Test and analyze uncontrolled dynamics systems in terms of sensor system order, time response, and stability using Laplace transformation and time domain calibration, and analysis									
		• •	·			indration, and	anarysis				
	6. Simulate the controlled dynamic system using Matlab7. Integrate, test, and analyze the controlled dynamic systems										
	I	-	-	Evalu	ation						
Ass	essment 7	Fools	Expected Du	Weight							
Hon	nework			15%							
Qui	zzes			15%							
Rep	orts			30 %							
Fina	al Exam -	+ Project		40 %							
		Contri	bution of Co	irse to Mee	t the Professi	ional Compo	onents				
The laboratory contributes to build the fundamentals in designing, realizing physical dynamical systems for both thermal											
	applied me d project.	chanical applic	ations. It also pr	omotes active	thinking in desig	gning control s	ystems by e	enforcing an open-			
ciluc	a project.		Relati	onshin to S	tudent Outco	mes					
	SOs	1	2	$\frac{1}{3}$	<u>г</u>	5	6	7			
	ilability	I X	X	3	4 5 6 X X X		/				
Ava	nability			ool Engino	ning Drogram						
Relationship to Mechanical Engineering Program Objectives (MEPOs)MEPO1MEPO2MEPO3MEPO4MEPO5								MEPO5			
1	An abili	ter ta idantife			Outcomes (SO	1	h	na nrinainles of			
1		• •	nd mathematics		iplex engineeri	ng problems	by applyi	ng principles of			
2	•				olutions that m	eet specified i	needs with	consideration of			
2	An ability to apply engineering design to produce solutions that meet specified needs with consideration of public health, safety, and welfare, as well as global, cultural, social, environmental, and economic factors										
3	An ability to communicate effectively with a range of audiences										
4											
-	judgments, which must consider the impact of engineering solutions in global, economic, environmental,										
		etal contexts			•	~ .					
5	An abili	ty to functio	n effectively o	n a team w	hose members	s together pro	ovide lead	lership, create a			
	collaborative and inclusive environment, establish goals, plan tasks, and meet objectives										
6	An ability to develop and conduct appropriate experimentation, analyze and interpret data, and use										
	engineering judgment to draw conclusions										
7	7 An ability to acquire and apply new knowledge as needed, using appropriate learning strategies										
	Updated by ABET Committee, 2024										